



Internship / Semester Project / Master Project

3D Upgrade: Assessment of hand and arm function using virtual reality and haptics

Zurich, October 2010

Goal: Upgrade an existing VR/haptics assessment tool to restore depth perception

Background information

Hand sensorimotor function is often severely impaired in people suffering from neurological disorders, e.g. following a stroke. The selection of an appropriate therapy to recover the lost abilities requires a detailed assessment of the functional deficits.

Conventional upper limb motor function assessments suffer from several limitations, including inter-rater variability and a lack of objectivity. We therefore propose to provide more objective and reliable tests by using robotic devices to assess hand and arm function.

The Rehabilitation Engineering Lab (RELab) has developed a novel test, the Virtual Peg Insertion Test, which combines virtual reality and haptics using the PHANTOM Omni (SensAble Technologies), a low-cost, general purpose haptic interface.





VR peg insertion test (RELab)

3D VISION kit (NVIDIA)

Project description

In order to improve the current test and increase its realism, we would like to render the task in 3D. This would require to adapt the existing C++ code and interface it to a wireless stereoscopic system with 3D vision glasses by NVIDIA.

The suitable candidate should have good knowledge of C++ programming and some experience in 3D systems.

We look forward to your application!

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